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Autonomous Robots | The MIT Press

Abstract Simple artificial creatures (‘animats’), which operate as autonomous, adaptive robots in the real world, can serve both as models of biology and as a radical alternative to conventional methods of designing intelligent systems. We describe the

evolution and implementation of the autonomous robot ARBIB, which learns from and adapts to its environment.

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ARBIB: An autonomous robot based on inspirations from ...

One key approach to the development of such intelligent and autonomous robots

draws inspiration from the behavior demonstration of biological systems. In fact, using this approach, a number of new application areas have recently received significant interest from the robotics community, including rehabilitation robots, service robots, medical robots, and entertainment robots.